

<https://doi.org/10.52326/ic-ecco.2022/CS.12>



# A Set of Smart Ring Gestures for Drone Control

Alexandru-Ionuț Șiean<sup>1</sup>, ORCID: 0000-0002-3166-7495

<sup>1</sup>MintViz Lab, MANSiD Research Center, Ștefan cel Mare University of Suceava, 13 Universitatii, Suceava 720229, Romania  
alexandru.siean@usm.ro

**Abstract**—We present in this paper the results of a frequency analysis of gesture commands frequently employed for human-drone interaction in the scientific literature, and we propose a set of gestures for controlling drones that can be performed with smart rings. Our method consists in the analysis of thirty-seven articles, which we examined closely to extract commands for human-drone interaction, including voice, gesture, and multimodal input. Based on our meta-analysis, we present a set of six groups of commands for human-drone interaction together with a set of smart ring gestures to interact with and control drones. Our results can be used to inform the design of new interactive applications for controlling smart-ring drones.

**Keywords**—user; human; drone; uav; interaction; control

## I. INTRODUCTION

Application with drones can improve the quality of life of the people that interact with these devices. The great advantage drones present is their ability to fly and implicitly move quickly from one location to another without human supervision. Therefore, we find applications in all domains with drones, such as intelligent transportation [1], live construction inspection [2], security [3], etc. Enriching the users' experiences regarding personal drones has a great effect on multiple domains, in which we find haptic feedback in Virtual Reality [4], Mixed Reality [5], taking selfies [6], etc. Therefore, motivated by the desire to integrate drones into public space and interact with them using devices other than conventional ones with which drones come in basic equipment e.g., a controller, we propose a set of gestures using smart rings for the most common commands in the literature that aim to control the drone in order to extend to new applications that include these wearable devices.

We believe that our inventory will be useful to researchers and practitioners interested in the gestural commands that are most commonly used to interact with the drone and our proposed set of smart ring gestures designed to execute these commands. Even with small drones such as Parrot Mambo FPV, illustrated in Figure 1, and with Smart Rings ZERO, applications can be created to enrich the dictionary of gestures proposed by us in order to make the perfect photo [7] or new applications of human-drone interaction.



Fig. 1. Parrot Mambo Fly personal drone and Smart Ring ZERO

## II. RELATED WORK

A wide variety of applications include human-drone interaction. These include: entertainment applications [8], [9], hands-free [10], emergency situation [11], search and rescue missions [12]. These applications recognize gesture commands [8], [9], [11], [12], voice commands [10], [13], [14], and even multimodal interactions [10], [15], [16], [17], [18]. User feedback is provided in different ways, such as visual [19], [20], haptic [4], [21], or with the help of a controller [22]. All these applications are intended to shape new ways of interacting with drones, such as using voice commands [13], multimodal interactions [15], or receiving feedback from the drone through different modes e.g., visual [20]. Therefore, this multitude of applications offer, in turn, a multitude of gestural commands that we have extracted and grouped to propose new ways to interact with drones using smart rings.

### A. Interaction modalities with Drone and Users in Studies

As the popularity of drones has grown, drones have become more and more present in our lives, being integrated into many applications. For example, photo/video [11], [19], user security [15], [23], etc. Therefore, drones have led to new applications and implicitly to new ways of interaction. From the analysis of the 37 papers, we extracted all the interaction ways presented in each scientific paper. In the third chapter, we explain the methodology for identifying and selecting

articles. Our results show that 81% of the interactions were gestural, 38% were multimodal, 27% used voice, 14% used a BCI/EEG headset, and 8% used mobile devices. For example, MohaimenianPour *et al.* [9] use a BCI/EEG neural headset for real-time detection of facial gestures to improve human-robot interaction. Brock *et al.* [17] propose an interactive map for drone users to open the space for more direct interactions with drones. The analysis of the thirty-seven papers continued users' perspectives in the studies; 46% of the papers did not report any participants in the study, even if they discussed a certain way of interaction. A total of 473 participants were reported. The maximum number of participants was 110 in the work of Peshkova *et al.* [14], in which he made a participatory design of the most intuitive ways to control a drone. A single participant was reported in the work of Higuchi *et al.* [24], who developed a system that directly connects body movement with drone movements.

### B. Type of Scientific Contributions for Drone Applications

The thirty-seven scientific papers were divided into the following categories: (1) empirical research, (2) artifact, (3) methodological, (4) theoretical, (5) data-set, (6) survey, and (7) opinion, according to Wobbrock *et al.* [25] classification. The greatest scientific contribution was of the type of empirical research found in 95% of the articles. Following the artifact, which was present in 16% of the articles, we found the design of a controller [26] and eye gaze tracking systems [19]. We classified 11% of the works as theoretical publications. The rest of the contributions were less representative. For example, we found the work of Lee *et al.* [27], which presents a new human gesture prediction framework using computer vision for the human-drone interaction where the set presents the date. This category represents 8% of the total number of works that complete the list of works [9], [28]. A single paper [29] has been classified as a survey proposing a graphical interface designed and centered on the human body for drone interactions. No paper has published a methodology or an opinion on human-drone interaction in our analysis.

## III. A SET OF SMART RING GESTURES FOR DRONE CONTROL

### A. Methodology

We surveyed the specialty literature to identify all commands whose purpose is human-drone interaction. We searched for the most popular international databases of scientific articles, ACM DL<sup>1</sup>, IEEE Xplore<sup>2</sup>, and SpringerLink<sup>3</sup>,

TABLE 1. DICTIONARY GESTURES DRONE ASSOCIATION WITH SMART RING

| Commands | Count <sup>1</sup> | One Ring Gestures |   | Two Rings Gestures                          |  | Description commands                           |                                       |
|----------|--------------------|-------------------|---|---|--|--|---------------------------------------|
|          |                    | First association | Second association                          | First association                           | Second association                             |  |                                       |
| C1       | forward            | 13                | Circle clockwise                            | Flick to the right                          | Circle clockwise                               | Touch both rings simultaneously                | The hands move away from the body     |
|          | backward           | 9                 | Circle counter-clockwise                    | Circle counter-clockwise                    | Circle counter-clockwise                       | Flick to the right using both hands            | The hands approach the body           |
| C2       | right              | 13                | Flick to the right                          | Clap once                                   | Flick to the left                              | Use the hands as a hands fan                   | Hand moves to the right               |
|          | left               | 11                | Flick to the left                           | Swipe on the ring upwards                   | Flick to the right                             | Raise hand and touch the ring                  | Hand moves to the left                |
| C3       | up                 | 9                 | Raise hand and touch the ring               | Touch the ring once                         | Touch both rings simultaneously                | Flick upwards                                  | Extends right hand                    |
|          | down               | 9                 | Touch the ring once and flick to the left   | Circle clockwise                            | Spread palms horizontally                      | Flick downwards                                | Extends left hands                    |
| C4       | fly higher         | 6                 | Clap once                                   | Raise hand and touch the ring               | Clap once                                      | Flick downwards using both hands               | The right hand rises next to the body |
|          | fly lower          | 6                 | Touch the ring once                         | Press imaginary button in mid-air           | Rub hands                                      | Circle clockwise                               | The right hand sits next on the body  |
| C5       | turn right         | 4                 | Draw letter "S" in mid-air <sup>3</sup>     | Touch the ring once and flick to the left   | Flick upwards                                  | Clap once                                      | Rotate right hand on the right        |
|          | turn left          | 4                 | "Call me" sign <sup>2</sup>                 | Press button on an imaginary remote control | Flick downwards                                | Rub hands                                      | Rotate left hand on the left          |
| C6       | take off           | 13                | Press button on an imaginary remote control | "Call me" sign <sup>2</sup>                 | Bring both hands in front and towards the body | Press several imaginary buttons in mid-air     | Index finger moves upwards            |
|          | land               | 9                 | Press imaginary button in mid-air           | Draw letter "S" in mid-air <sup>3</sup>     | Press several imaginary buttons in mid-air     | Bring both hands in front and towards the body | The two hands form a rectangle        |

<sup>1</sup>Total number of gesture commands from specialty literature.

<sup>2</sup>Thumb placed near the ear, little finger pointed at the mouth; <sup>3</sup>Letter "S" stands for "Security.", Gheran et al. [45].

<sup>1</sup><https://dl.acm.org/>

<sup>2</sup><https://ieeexplore.ieee.org/Xplore/home.jsp>

<sup>3</sup><https://link.springer.com/>

using:

```
"query": {
  Abstract: ((user OR human) AND
    (drone OR UAV) AND (Interaction
    OR Control))
}
"filter": {NOT VirtualContent: true}
```

Following the query of the three databases, we analyzed from the title and abstract the articles that would be of interest to us. We saved 105 papers published between 2002 and 2021 that target the human-drone interaction from this analysis. The 37 papers that we analyze in detail present commands for interaction with drones. Therefore, the discussion was limited to articles showing the gestural human-drone interaction. The total number of commands extracted from the thirty-seven articles was 341. Investigating the articles, extracting orders, and proposing gestures with smart rings is the major contribution of this paper.

### B. Results

We grouped the commands most frequently encountered in the specialty literature whose purpose is the interaction between human and drone in six categories; see Table 1.

- C<sub>1</sub>: - *'forward/backward'*, the drone moves forward or back [6], [8], [11], [14], [29], [30], [31], [32], [33], [34], [35], [5], [24], [14].
- C<sub>2</sub>: - *'right/left'*, drone moves left or right [8], [23], [11], [14], [29], [30], [31], [32], [33], [34], [35], [5], [24], [14], [14].
- C<sub>3</sub>: - *'up/down'*, raises or lowers the altitude of the drone [32], [33], [34], [12], [24], [14], [28], [22], [36], [37].
- C<sub>4</sub>: - *'fly higher/fly lower'*, the drone raises/decreases altitude but moves forward/back [13], [15], [16], [38], [39], [14].
- C<sub>5</sub>: - *'turn right/turn left'*, drone spins around its axis to right or left [8], [40], [22], [37].
- C<sub>6</sub>: - *'take off/land'* includes the launch of the drone for flight [8], [13], [15], [16], [27], [30], [31], [32], [41], [14], [42], [37].

Table 1 shows the commands most frequently met identified in our survey (thirty-seven articles out of one hundred and five) grouped into six categories, followed by two gesture proposals using a single smart ring, and two gesture proposals that are made with two smart rings, and the last column describes the gesture. The results of our study show that the distribution of commands in terms of frequency is uneven. For example, in categories C<sub>1</sub>, C<sub>2</sub>, and C<sub>6</sub> we find the most frequent commands in the literature: forward, right, and take off. We notice that the categories C<sub>1</sub>, C<sub>3</sub>, C<sub>5</sub>, and C<sub>6</sub> present the most uniform distribution of commands so far, followed by C<sub>4</sub> with the least used gesture commands. Note that the other commands were also present in the literature e.g.,

'fly-where-you-look' [19], 'precise location' [15], 'speed and hover' [20], [43], 'continue and take a picture' [12], [9], but we have focused on the most common. Therefore, for each category, we proposed four gestures using smart rings. Two gestures with a single ring are proposed and the other two with two smart rings. Associating smart-ring gestures with drone commands opens up new ways to interact with smart rings. The four proposals for smart ring gestures for the most common gesture commands in the literature are taken from the work of Gheran *et al.* [44], [45]. In which he presents a detailed study of smart ring gestures. The association of gestures with drone commands is our proposal to researchers to form new applications and interactions that include gestures with smart rings and drones.

### IV. CONCLUSION AND FUTURE WORK

In this paper we have presented the six categories of gestures that control drones, and for each we have proposed a set of commands using smart rings. Our study covered thirty-seven papers out of one hundred returned by queries to international databases according to the methodology in chapter three. Our work implements an important step in the human-drone interaction using smart rings, but also the effective proposal of the gestures that will be used for the most frequent control commands of the drone. Our study continued with the analysis of the type of article in which the researchers described their work, the type of gestures that were encountered in human-drone interaction, and also the number of study participants. These metrics are useful for extending new smart ring gesture sets. Our next plan is to implement an application to control the Parrot Mambo FPV drone with SDK available for Android<sup>4</sup>, and its control with Smart Rings ZERO, present in Figure 1, also using SDK for Android. After the implementation of this application, we want to conduct studies with users in which to propose new gestures with smart rings for the most frequent drone control commands. Continuing these ideas will lead to new gesture input models using smart rings for human-drone interaction.

### V. ACKNOWLEDGMENTS

This work is supported by the project ANTREPENORDOC, in the framework of Human Resources Development Operational Programme 2014-2020, financed from the European Social Fund under the contract number 36355/23.05.2019 HRD OP /380/6/13 – SMIS Code: 123847.

### REFERENCES

- [1] V. Baboolal, K. Akkaya, N. Saputro, and K. Rabieh, "Preserving privacy of drone videos using proxy re-encryption technique: Poster," in *Proceedings of the 12th Conference on Security and Privacy in Wireless and Mobile Networks*, ser. WiSec '19. New York, NY, USA: Association for Computing Machinery, 2019, p. 336–337. [Online]. Available: <https://doi.org/10.1145/3317549.3326319>
- [2] S. George, J. Wang, M. Bala, T. Eiszler, P. Pillai, and M. Satyanarayanan,

- “Towards drone-sourced live video analytics for the construction industry,” in *Proceedings of the 20th International Workshop on Mobile Computing Systems and Applications*, ser. HotMobile '19. New York, NY, USA: Association for Computing Machinery, 2019, p. 3–8. [Online]. Available: <https://doi.org/10.1145/3301293.3302365>
- [3] R. Majeed, N. Abdullah, M. Mushtaq, and R. Kazmi, “Drone security: Issues and challenges,” *International Journal of Advanced Computer Science and Applications*, vol. 12, 06 2021.
- [4] E. Tsykunov and D. Tsetserukou, “Wiredswarm: High resolution haptic feedback provided by a swarm of drones to the user’s fingers for vr interaction,” in *25th ACM Symposium on Virtual Reality Software and Technology*, ser. VRST '19. New York, NY, USA: Association for Computing Machinery, 2019. [Online]. Available: <https://doi.org/10.1145/3359996.3364789>
- [5] B. Jones, K. Dillman, R. Tang, A. Tang, E. Sharlin, L. Oehlberg, C. Neustaedter, and S. Bateman, “Elevating communication, collaboration, and shared experiences in mobile video through drones,” in *Proceedings of the 2016 ACM Conference on Designing Interactive Systems*, ser. DIS '16. New York, NY, USA: Association for Computing Machinery, 2016, p. 1123–1135. [Online]. Available: <https://doi.org/10.1145/2901790.2901847>
- [6] C.-F. Chen, K.-P. Liu, and N.-H. Yu, “Exploring interaction modalities for a selfie drone,” in *SIGGRAPH Asia 2015 Posters*, ser. SA '15. New York, NY, USA: Association for Computing Machinery, 2015. [Online]. Available: <https://doi.org/10.1145/2820926.2820965>
- [7] A.-I. Sean, R.-D. Vatavu, and J. Vanderdonck, “Taking that perfect aerial photo: A synopsis of interactions for drone-based aerial photography and video,” in *ACM International Conference on Interactive Media Experiences*, ser. IMX '21. New York, NY, USA: Association for Computing Machinery, 2021, p. 275–279. [Online]. Available: <https://doi.org/10.1145/3452918.3465484>
- [8] M. De Marsico and A. Spagnoli, “Using hands as an easy uav joystick for entertainment applications,” in *Proceedings of the 13th Biannual Conference of the Italian SIGCHI Chapter: Designing the next Interaction*, ser. CHIItaly '19. New York, NY, USA: Association for Computing Machinery, 2019. [Online]. Available: <https://doi.org/10.1145/3351995.3352042>
- [9] S. MohaimenianPour and R. Vaughan, “Hands and faces, fast: Monocamera user detection robust enough to directly control a uav in flight,” in *2018 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. IEEE Press, 2018, p. 5224–5231. [Online]. Available: <https://doi.org/10.1109/IROS.2018.8593709>
- [10] M. Landau and S. van Delden, “A system architecture for hands-free uav drone control using intuitive voice commands,” in *Proceedings of the Companion of the 2017 ACM/IEEE International Conference on Human-Robot Interaction*, ser. HRI '17. New York, NY, USA: Association for Computing Machinery, 2017, p. 181–182. [Online]. Available: <https://doi.org/10.1145/3029798.3038329>
- [11] Y. Yu, X. Wang, Z. Zhong, and Y. Zhang, “Ros-based uav control using hand gesture recognition,” in *2017 29th Chinese Control And Decision Conference (CCDC)*, 2017, pp. 6795–6799.
- [12] J. Cacace, A. Finzi, V. Lippiello, M. Furci, N. Mimmo, and L. Marconi, “A control architecture for multiple drones operated via multimodal interaction in search amp; rescue mission,” in *2016 IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR)*, 2016, pp. 233–239.
- [13] P. Abtahi, D. Y. Zhao, J. L. E., and J. A. Landay, “Drone near me: Exploring touch-based human-drone interaction,” *Proc. ACM Interact. Mob. Wearable Ubiquitous Technol.*, vol. 1, no. 3, sep 2017. [Online]. Available: <https://doi.org/10.1145/3130899>
- [14] E. Peshkova, M. Hitz, and D. Ahlström, “Exploring user-defined gestures and voice commands to control an unmanned aerial vehicle,” in *Intelligent Technologies for Interactive Entertainment*, R. Poppe, J.-J. Meyer, R. Veltkamp, and M. Dastani, Eds. Cham: Springer International Publishing, 2017, pp. 47–62.
- [15] J. R. Cauchard, J. L. E., K. Y. Zhai, and J. A. Landay, “Drone & me: An exploration into natural human-drone interaction,” in *Proceedings of the 2015 ACM International Joint Conference on Pervasive and Ubiquitous Computing*, ser. UbiComp '15. New York, NY, USA: Association for Computing Machinery, 2015, p. 361–365. [Online]. Available: <https://doi.org/10.1145/2750858.2805823>
- [16] J. L. E., I. L. E., J. A. Landay, and J. R. Cauchard, “Drone & wo: Cultural influences on human-drone interaction techniques,” in *Proceedings of the 2017 CHI Conference on Human Factors in Computing Systems*, ser. CHI '17. New York, NY, USA: Association for Computing Machinery, 2017, p. 6794–6799. [Online]. Available: <https://doi.org/10.1145/3025453.3025755>
- [17] A. M. Brock, J. Chatain, M. Park, T. Fang, M. Hachet, J. A. Landay, and J. R. Cauchard, “Flymap: Interacting with maps projected from a drone,” in *Proceedings of the 7th ACM International Symposium on Pervasive Displays*, ser. PerDis '18. New York, NY, USA: Association for Computing Machinery, 2018. [Online]. Available: <https://doi.org/10.1145/3205873.3205877>
- [18] E. O’Keeffe, A. Campbell, D. Swords, D. F. Laefer, and E. Mangina, “Oculus rift application for training drone pilots,” in *Proceedings of the 10th EAI International Conference on Simulation Tools and Techniques*, ser. SIMUTOOLS '17. New York, NY, USA: Association for Computing Machinery, 2017, p. 77–80. [Online]. Available: <https://doi.org/10.1145/3173519.3173531>
- [19] A. Alapetite, J. P. Hansen, and I. S. MacKenzie, “Demo of gaze controlled flying,” in *Proceedings of the 7th Nordic Conference on Human-Computer Interaction: Making Sense Through Design*, ser. NordiCHI '12. New York, NY, USA: Association for Computing Machinery, 2012, p. 773–774. [Online]. Available: <https://doi.org/10.1145/2399016.2399140>
- [20] J. P. Hansen, A. Alapetite, I. S. MacKenzie, and E. Møllenbach, “The use of gaze to control drones,” in *Proceedings of the Symposium on Eye Tracking Research and Applications*, ser. ETRA '14. New York, NY, USA: Association for Computing Machinery, 2014, p. 27–34. [Online]. Available: <https://doi.org/10.1145/2578153.2578156>
- [21] G. Gubcsi and T. Zsedrovits, “Ergonomic quadcopter control using the leap motion controller,” 06 2018, pp. 1–5.
- [22] B. Hu and J. Wang, “Deep learning based hand gesture recognition and uav flight controls,” *International Journal of Automation and Computing*, vol. 17, 09 2019.
- [23] M. Monajjemi, S. Mohaimenianpour, and R. Vaughan, “Uav, come to me: End-to-end, multi-scale situated hri with an uninstrumented human and a distant uav,” in *2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, 2016, pp. 4410–4417.
- [24] K. Higuchi, K. Fujii, and J. Rekimoto, “Flying head: A head-synchronization mechanism for flying telepresence,” 12 2013, pp. 28–34.
- [25] J. O. Wobbrock and J. A. Kientz, “Research contributions in human-computer interaction,” *Interactions*, vol. 23, no. 3, p. 38–44, apr 2016. [Online]. Available: <https://doi.org/10.1145/2907069>
- [26] C. Anderson, B. Barash, C. McNeill, D. Ogun, M. Wray, J. Knibbe, C. H. Morris, and S. A. Seah, “The cage: Towards a 6-dof remote control with force feedback for uav interaction,” in *Proceedings of the 33rd Annual ACM Conference Extended Abstracts on Human Factors in Computing Systems*, ser. CHI EA '15. New York, NY, USA: Association for Computing Machinery, 2015, p. 1687–1692. [Online]. Available: <https://doi.org/10.1145/2702613.2732877>
- [27] J. Lee, H. Tan, D. Crandall, and S. Šabanović, “Forecasting hand gestures for human-drone interaction,” in *Companion of the 2018 ACM/IEEE International Conference on Human-Robot Interaction*, ser. HRI '18. New York, NY, USA: Association for Computing Machinery, 2018, p. 167–168. [Online]. Available: <https://doi.org/10.1145/3173386.3176967>
- [28] A. Perera, Y. W. Law, and J. Chahl, “Uav-gesture: A dataset for uav control and gesture recognition,” 01 2019, pp. 117–128.
- [29] J. R. Cauchard, A. Tamkin, C. Y. Wang, L. Vink, M. Park, T. Fang, and J. A. Landay, “Drone.io: A gestural and visual interface for human-drone interaction,” in *2019 14th ACM/IEEE International Conference on Human-Robot Interaction (HRI)*, 2019, pp. 153–162.
- [30] A. Mashood, H. Noura, I. Jawhar, and N. Mohamed, “A gesture based kinect for quadrotor control,” in *2015 International Conference on Information and Communication Technology Research (ICTRC)*, 2015, pp. 298–301.
- [31] R. Suarez Fernandez, J. Sanchez-Lopez, C. Sampedro Pérez, H. Bawle, M. Molina, and P. Campoy, “Natural user interfaces for human-drone multi-modal interaction,” 06 2016, pp. 1013–1022.
- [32] S. Zhang, X. Liu, J. Yu, L. Zhang, and X. Zhou, “Research on multi-modal interactive control for quadrotor uav,” in *2019 IEEE 16th International Conference on Networking, Sensing and Control (ICNSC)*, 2019, pp. 329–334.

- [33] V. L. Popov, K. B. Shiev, A. V. Topalov, N. G. Shakev, and S. A. Ahmed, "Control of the flight of a small quadrotor using gestural interface," in *2016 IEEE 8th International Conference on Intelligent Systems (IS)*, 2016, pp. 622–628.
- [34] S.-Y. Shin, Y.-W. Kang, and Y.-G. Kim, "Hand gesture-based wearable human-drone interface for intuitive movement control," in *2019 IEEE International Conference on Consumer Electronics (ICCE)*, 2019, pp. 1–6.
- [35] H. Kang, H. Li, J. Zhang, X. Lu, and B. Benes, "Flycam: Multitouch gesture controlled drone gimbal photography," *IEEE Robotics and Automation Letters*, vol. 3, no. 4, pp. 3717–3724, 2018.
- [36] B. Sanders, D. Vincenzi, and Y. Shen, "Investigation of gesture based uav control," 07 2018, pp. 205–215.
- [37] V. E. Nahapetyan and V. Khachumov, "Gesture recognition in the problem of contactless control of an unmanned aerial vehicle," *Optoelectronics, Instrumentation and Data Processing*, vol. 51, pp. 192–197, 2015.
- [38] M. Seuter, E. R. Macrillante, G. Bauer, and C. Kray, "Running with drones: Desired services and control gestures," in *Proceedings of the 30th Australian Conference on Computer-Human Interaction*, ser. OzCHI '18. New York, NY, USA: Association for Computing Machinery, 2018, p. 384–395. [Online]. Available: <https://doi.org/10.1145/3292147.3292156>
- [39] J. Bruce, J. Perron, and R. Vaughan, "Ready—aim—fly! hands-free face-based hri for 3d trajectory control of uavs," in *2017 14th Conference on Computer and Robot Vision (CRV)*, 2017, pp. 307–313.
- [40] G. Costante, E. Bellocchio, P. Valigi, and E. Ricci, "Personalizing vision-based gestural interfaces for hri with uavs: a transfer learning approach," in *2014 IEEE/RSJ International Conference on Intelligent Robots and Systems*, 2014, pp. 3319–3326.
- [41] W. S. Ng and E. Sharlin, "Collocated interaction with flying robots," in *2011 RO-MAN*, 2011, pp. 143–149.
- [42] A. Maher, C. Li, H. Hu, and B. Zhang, "Realtime human-uav interaction using deep learning," 10 2017, pp. 511–519.
- [43] M. Agor, D. Clergeaud, A. Clée, and M. Hachet, "Human-drones interaction for gravity-free juggling," in *Proceedings of the 29th Conference on l'Interaction Homme-Machine*, ser. IHM '17. New York, NY, USA: Association for Computing Machinery, 2017, p. 309–314. [Online]. Available: <https://doi.org/10.1145/3132129.3132163>
- [44] B.-F. Gheran, J. Vanderdonckt, and R.-D. Vatavu, "Gestures for smart rings: Empirical results, insights, and design implications," in *Proceedings of the 2018 Designing Interactive Systems Conference*, ser. DIS '18. New York, NY, USA: Association for Computing Machinery, 2018, p. 623–635. [Online]. Available: <https://doi.org/10.1145/3196709.3196741>
- [45] B.-F. Gheran, R.-D. Vatavu, and J. Vanderdonckt, "Ring x2: Designing gestures for smart rings using temporal calculus," 05 2018, pp. 117–122.